

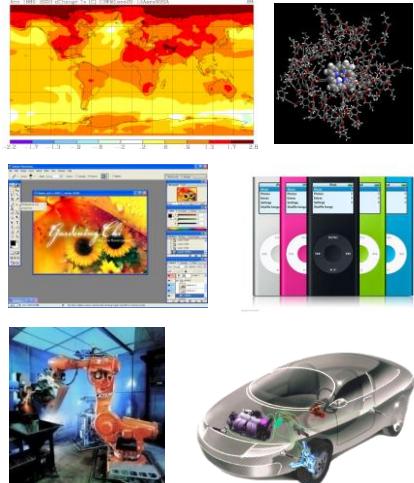
# Program Generation for Performance Spiral

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## Mathematical Computing



Science simulations

Audio, image, Video processing

Signal processing, communication, control

Security

Machine learning, data analytics

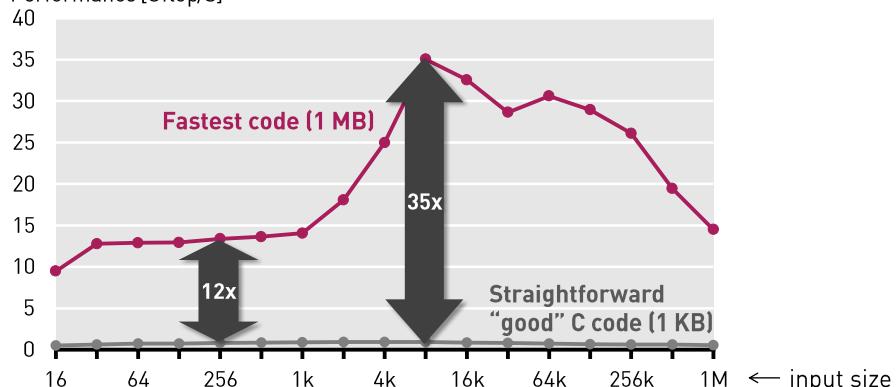
Optimization

***Highest performance  
is often crucial***

## Example: Discrete Fourier Transform

DFT (single precision) on Intel Core i7 (4 cores, 2.66 GHz)

Performance [Gflop/s]

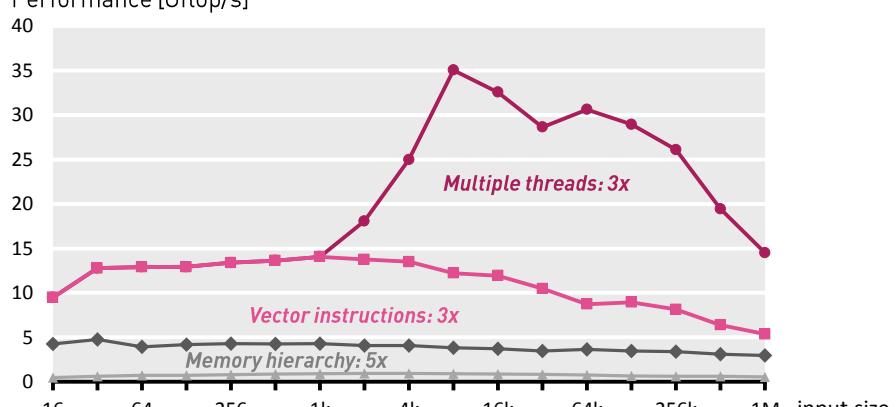


Vendor compiler, best flags

Roughly same operations count

DFT (single precision) on Intel Core i7 (4 cores, 2.66 GHz)

Performance [Gflop/s]



Compiler doesn't do the job

**Doing by hand** = restructure algorithm for locality & parallelism,  
handle choices, choose proper code style, use vector intrinsics, ....  
**= nightmare**

Model predictive control	Singular-value decomposition
Eigenvalues	Mean shift algorithm for segmentation
LU factorization	Stencil computations
Optimal binary search organization	Displacement based algorithms
Image color conversions	Motion estimation
Image geometry transformations	Multiresolution classifier
Enclosing ball of points	Kalman filter
Metropolis algorithm, Monte Carlo	Object detection
Seam carving	IIR filters
SURF feature detection	Arithmetic for large numbers
Submodular function optimization	Optimal binary search organization
Graph cuts, Edmond-Karps Algorithm	Software defined radio
Gaussian filter	Shortest path problem
Black Scholes option pricing	Feature set for biomedical imaging
Disparity map refinement	Biometrics identification

Same for most computational problems:  
**Straightforward code is highly suboptimal**

## Optimization: Register Locality and ILP

```
// straightforward code
for(i = 0; i < N; i += 1)
    for(j = 0; j < N; j += 1)
        for(k = 0; k < N; k += 1)
            c[i][j] += a[i][k]*b[k][j];
```

*Concise and slow*

Removes aliasing

Enables register allocation and instruction scheduling

*Compiler does not do well:*

- often illegal
- many choices

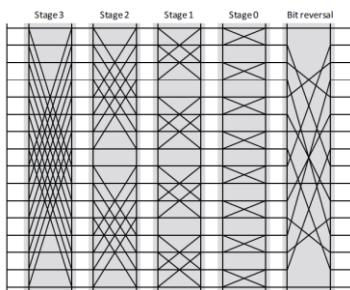
```
// unrolling + scalar replacement
for(i = 0; i < N; i += MU) {
    for(j = 0; j < N; j += NU) {
        for(k = 0; k < N; k += KU) {
            t1 = A[i*N + k];
            t2 = A[i*N + k + 1];
            t3 = A[i*N + k + 2];
            t4 = A[i*N + k + 3];
            t5 = A[(i + 1)*N + k];
            <more copies>
        }
    }
}
```

```
t10 = t1 * t9;
t17 = t17 + t10;
t21 = t1 * t8;
t18 = t18 + t21;
t12 = t5 * t9;
t19 = t19 + t12;
t13 = t5 * t8;
t20 = t20 + t13;
<more ops>
```

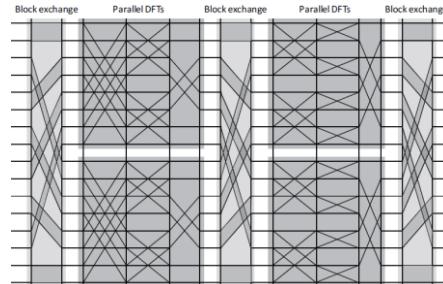
```
C[i*N + j]      = t17;
C[i*N + j + 1]  = t18;
C[(i+1)*N + j] = t19;
C[(i+1)*N + j + 1] = t20;
```

*Ugly and fast*

## Optimization for Parallelism (Threads)



Parallelism is present, but is not in the “right shape”



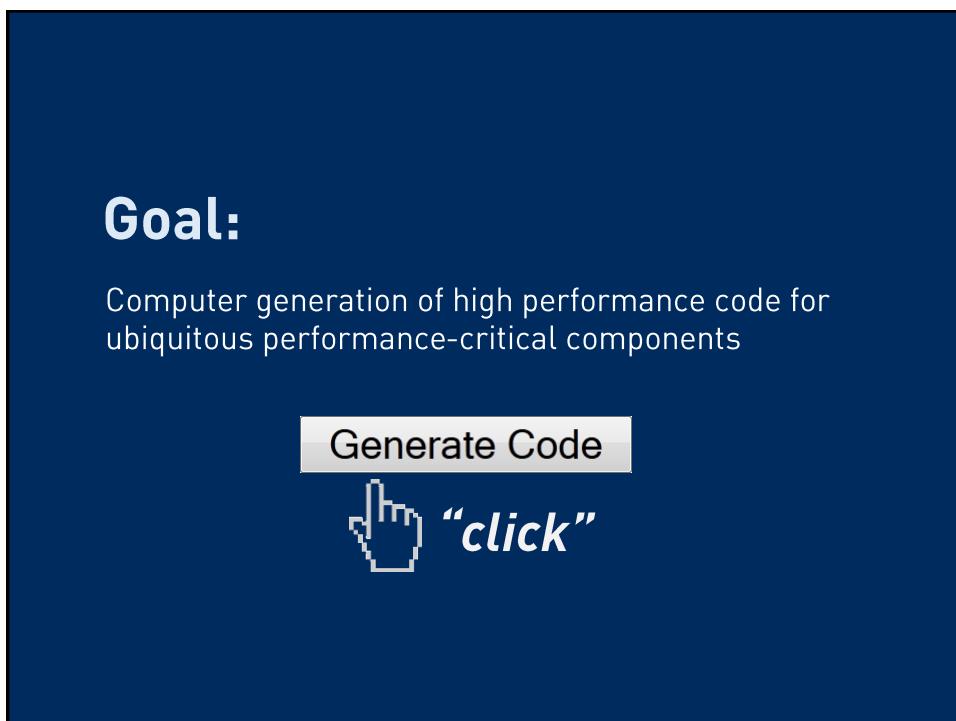
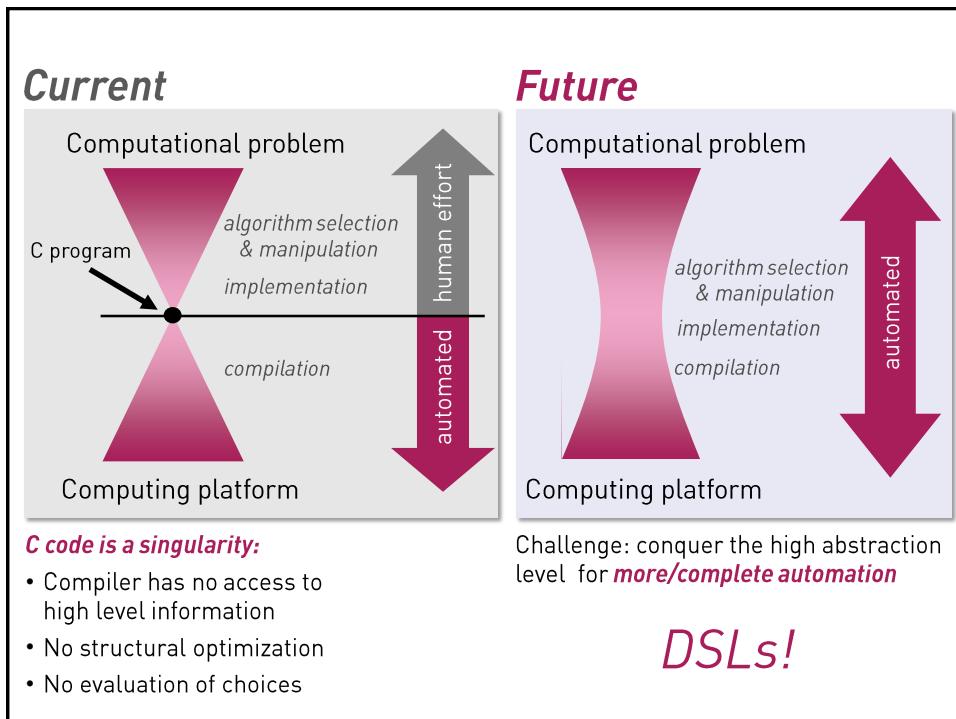
Restructured for locality and parallelism (shared memory, 2 cores, 2 elements per cache line)

*Compiler usually does not do*

- analysis may be unfeasible
- may require algorithm changes
- may require domain knowledge
- may require processor parameters

***Current practice:*** Thousands of programmers re-implement and re-optimize the same functionality for every new processor and for every new processor generation





**Select convolutional code**  
Select a preset code or customize parameters

<input type="radio"/> custom	rate	1 / <input type="text" value="2"/>	code rate <a href="#">(?)</a>
<input checked="" type="radio"/> Voyager	K	<input type="text" value="7"/>	constraint length <a href="#">(?)</a>
<input type="radio"/> NASA-DSN	polynomials	<input type="text" value="109"/>	polynomials for the code in decimal notation <a href="#">(?)</a>
<input type="radio"/> CCSDS/NASA-GSFC		<input type="text" value="79"/>	
<input type="radio"/> WiMax			
<input type="radio"/> CDMA IS-95A			
<input type="radio"/> LTE (3GPP - Long Term Evolution)			
<input type="radio"/> UWB (802.15)			
<input type="radio"/> CDMA 2000			
<input type="radio"/> Cassini			
<input type="radio"/> Mars Pathfinder & Stereo			

**Select implementation options**

frame length	<input type="text" value="2048"/>	unpadded frame length	
Vectorization level	<input type="text" value="scalar C"/>	type of code <a href="#">(?)</a>	

**Viterbi Decoder**

**DFT IP Cores**

parameter	value	range	explanation
<b>Problem specification</b>			
transform size	<input type="text" value="64"/>	4-32768	Number of samples <a href="#">(?)</a>
direction	<input type="text" value="forward"/>		forward or inverse DFT <a href="#">(?)</a>
data type	<input type="text" value="fixed point"/>		fixed or floating point <a href="#">(?)</a>
	<input type="text" value="16"/>	4-32 bits	fixed point precision <a href="#">(?)</a>
	<input type="text" value="bits"/>		scaling mode <a href="#">(?)</a>
	<input type="text" value="unscaled"/>		
<b>Parameters controlling implementation</b>			
architecture	<input type="text" value="fully streaming"/>		iterative or fully streaming <a href="#">(?)</a>
radix	<input type="text" value="2"/>	2, 4, 8, 16, 32, 64	size of DFT basic block <a href="#">(?)</a>
streaming width	<input type="text" value="2"/>	2-64	number of complex words per cycle <a href="#">(?)</a>
data ordering	<input type="text" value="natural in / natural out"/>		natural or digit-reversed data order <a href="#">(?)</a>
BRAM budget	<input type="text" value="1000"/>		maximum # of BRAMs to utilize (-1 for no limit) <a href="#">(?)</a>

[Generate Verilog](#) [Reset](#)

[@ www.spiral.net](http://www.spiral.net)

## Possible Approach:

Capturing algorithm knowledge:  
*Domain-specific languages (DSLs)*

Structural optimization:  
*Rewriting systems*

High performance code style:  
*Compiler*

Decision making for choices:  
*Machine learning*

## Spiral: Program Generation for Performance ([www.spiral.net](http://www.spiral.net))



Franz Franchetti  
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Bryan Singer  
Srinivas Chellappa  
Frédéric de Mesmay  
Peter Milder  
José Moura  
David Padua  
Jeremy Johnson  
James Hoe  
<many more>

funding: DARPA, NSF, ONR, Intel

## Linear Transforms

$$\begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix} = y = Tx \longleftrightarrow T \cdot \begin{pmatrix} x_0 \\ x_1 \\ \vdots \\ x_{n-1} \end{pmatrix} = x$$

*Output*   *Input*

**Example:**  $T = \text{DFT}_n = [e^{-2k\ell\pi i/n}]_{0 \leq k, \ell < n}$

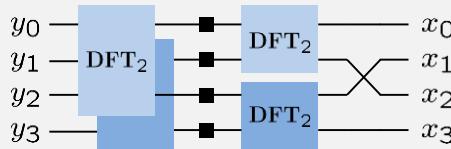
## Algorithms: Example FFT, n = 4

**Fast Fourier transform (FFT):**

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & i & -1 & -i \\ 1 & -1 & 1 & -1 \\ 1 & -i & -1 & i \end{bmatrix} x = \begin{bmatrix} 1 & . & 1 & . \\ . & 1 & . & 1 \\ 1 & . & -1 & . \\ . & 1 & . & -1 \end{bmatrix} \begin{bmatrix} 1 & . & . & . \\ . & 1 & . & . \\ . & . & 1 & . \\ . & . & . & i \end{bmatrix} \begin{bmatrix} 1 & 1 & . & . \\ 1 & -1 & . & . \\ . & 1 & 1 & 1 \\ . & 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & . & . & . \\ . & 1 & . & . \\ . & . & 1 & . \\ . & . & . & 1 \end{bmatrix} x$$

12 adds, 4 mults      4 adds      1 mult      4 adds      0 adds/mults

**Data flow graph**



**Description with matrix algebra (SPL)**

$$\text{DFT}_4 = (\text{DFT}_2 \otimes \text{I}_2) \text{T}_2^4 (\text{I}_2 \otimes \text{DFT}_2) \text{L}_2^4$$

## Decomposition Rules (>200 for >40 Transforms)

$$\begin{aligned}
& \text{DFT}_n \rightarrow P_{k/2,2m}^\top (\text{DFT}_{2m} \oplus (I_{k/2-1} \otimes_i C_{2m} \text{rDFT}_{2m}(i/k))) (\text{RDFT}'_k \otimes I_m), \quad k \text{ even}, \\
& \begin{cases} \text{RDFT}'_n \\ \text{DHT}'_n \\ \text{DHT}_n \\ \text{DHT}'_n \end{cases} \rightarrow (P_{k/2,m}^\top \otimes I_2) \left( \begin{cases} \text{RDFT}'_{2m} \\ \text{DHT}'_{2m} \\ \text{DHT}_{2m} \\ \text{DHT}'_{2m} \end{cases} \oplus \left( I_{k/2-1} \otimes_i D_{2m} \begin{cases} \text{rDFT}_{2m}(i/k) \\ \text{rDFT}_{2m}(i/k) \end{cases} \right) \right) \left( \begin{cases} \text{RDFT}'_k \\ \text{DHT}'_k \\ \text{DHT}_k \end{cases} \otimes I_m \right), \quad k \text{ even}, \\
& \begin{cases} \text{rDFT}_{2n}(u) \\ \text{rDHT}_{2n}(u) \end{cases} \rightarrow L_m^{2n} \left( I_k \otimes \begin{cases} \text{rDFT}_{2m}((i+u)/k) \\ \text{rDHT}_{2m}((i+u)/k) \end{cases} \right) \left( \begin{cases} \text{rDFT}_{2k}(u) \\ \text{rDHT}_{2k}(u) \end{cases} \otimes I_m \right), \\
& \text{RDFT-3}_n \rightarrow (Q_{k/2,m}^\top \otimes I_2) (I_k \otimes \text{rDFT}_{2m})(i + 1/2)/k)) (\text{RDFT-3}_k \otimes I_m), \quad k \text{ even}, \\
& \text{DCT-2}_n \rightarrow P_{k/2,m}^\top (\text{DCT-2}_{2m} K_2^{2m} \oplus (I_{k/2-1} \otimes N_{2m} \text{RDFT-3}_m^\top)) B_n (I_{k/2}^{n/2} \otimes I_2) (I_m \otimes \text{RDFT}'_k) Q_{m/2,k}, \\
& \text{DCT-3}_n \rightarrow Q_{k/2,2m}^\top (I_{k/2} \otimes N_{2m} \text{RDFT-3}_m) B_n (I_{k/2} \otimes I_2) (I_m \otimes \text{RDFT-3}_k) Q_{m/2,k}, \\
& \text{Rules = algorithm knowledge} \\
& \text{DCT-4}_n \rightarrow Q_{k/2,2m}^\top (I_{k/2} \otimes N_{2m} \text{RDFT-3}_m) B_n (I_{k/2} \otimes I_2) (I_m \otimes \text{RDFT-3}_k) Q_{m/2,k}. \\
& \text{DFT}_n \rightarrow P_n (\text{DFT}_k \otimes \text{DFT}_m) Q_{nm}, \quad n = km, \quad \gcd(k,m) = 1 \\
& \text{DFT}_p \rightarrow R_p^\top (I_1 \oplus \text{DFT}_{p-1}) D_p (I_1 \oplus \text{DFT}_{p-1}) R_p, \quad p \text{ prime} \\
& \text{DCT-3}_n \rightarrow (I_m \oplus J_m) L_m^n (\text{DCT-3}_m(1/4) \oplus \text{DCT-3}_m(3/4)) \\
& \quad \cdot (F_2 \otimes I_m) \begin{bmatrix} I_m & 0 \oplus -J_{m-1} \\ 0 & \frac{1}{\sqrt{2}}(I_1 \otimes 2I_m) \end{bmatrix}, \quad n = 2m \\
& \text{DCT-4}_n \rightarrow S_n \text{DCT-2}_n \text{diag}_{0 \leq k < n} (1/(2 \cos((2k+1)\pi/4n))) \\
& \text{IMDCT}_{2m} \rightarrow (J_m \oplus I_m \oplus I_m \oplus J_m) \left( \left( \begin{bmatrix} 1 \\ -1 \end{bmatrix} \otimes I_m \right) \oplus \left( \begin{bmatrix} -1 \\ 1 \end{bmatrix} \otimes I_m \right) \right) J_{2m} \text{DCT-4}_{2m} \\
& \text{WHT}_{2^k} \rightarrow \prod_{i=1}^t (I_{2^{k_1+\dots+k_{i-1}}} \otimes \text{WHT}_{2^{k_i}} \otimes I_{2^{k_{i+1}+\dots+k_t}}), \quad k = k_1 + \dots + k_t \\
& \text{DFT}_2 \rightarrow F_2 \\
& \text{DCT-2}_2 \rightarrow \text{diag}(1, 1/\sqrt{2}) F_2 \\
& \text{DCT-4}_2 \rightarrow J_2 R_{13\pi/8}
\end{aligned}$$

## SPL to Code

**SPL S** Pseudo code for  $y = Sx$

$A_n B_n$       <code for:  $t = Bx$ >  
 <code for:  $y = At$ >

$I_m \otimes A_n$       for ( $i=0$ ;  $i < m$ ;  $i++$ )  
 <code for:  
 $y[i:n:1:i*n+n-1] = A(x[i*n:1:i*n+n-1])$ >

$A_m \otimes I_n$       for ( $i=0$ ;  $i < n$ ;  $i++$ )  
 <code for:  
 $y[i:n:i+m*n-n] = A(x[i:n:i+m*n-n])$ >

$D_n$       for ( $i=0$ ;  $i < n$ ;  $i++$ )  
 $y[i] = D[i]*x[i];$

$L_k^{km}$       for ( $i=0$ ;  $i < k$ ;  $i++$ )  
 for ( $j=0$ ;  $j < m$ ;  $j++$ )  
 $y[i*m+j] = x[j*k+i];$

$F_2$        $y[0] = x[0] + x[1];$   
 $y[1] = x[0] - x[1];$

$$I_m \otimes A_n = \begin{bmatrix} A_n & & \\ & \ddots & \\ & & A_n \end{bmatrix}$$

*Gives reasonable, straightforward code*

## Program Generation in Spiral

Transform

$DFT_8$

*Decomposition rules (algorithm knowledge)*

Algorithm  
(SPL)

$(DFT_2 \otimes I_4) T_4^8 (I_2 \otimes ((DFT_2 \otimes I_2) T_2^4 (I_2 \otimes DFT_2) L_2^4)) L_2^8$

parallelization  
vectorization

Algorithm  
(-SPL)

$\sum (S_j DFT_2 G_j) \sum (\sum (S_{k,l} \text{diag}(t_{k,l}) DFT_2 G_l) \sum (S_m \text{diag}(t_m) DFT_2 G_{k,m}))$

locality  
optimization

C Program

```
void sub(double *y, double *x) {
    double f0, f1, f2, f3, f4, f7, f8, f10, f11;
    f0 = x[0] - x[3];
    f1 = x[0] + x[3];
    f2 = x[1] - x[2];
    f3 = x[1] + x[2];
    f4 = f1 - f3;
    y[0] = f1 + f3;
    y[2] = 0.7071067811865476 * f4;
    f7 = 0.9238795325112867 * f0;
    < more lines >
```

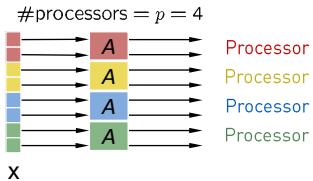
code style  
code level  
optimization

+ Search or  
Learning for  
Choices

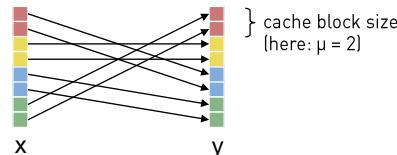
## SPL to Shared Memory Code: Basic Idea

*"Good" SPL structures*

$$y = (I_p \otimes A)x$$



$$y = (P \otimes I_\mu)x$$

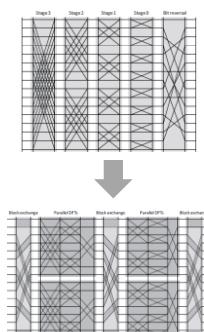


*Rewriting:* Bad structures good structures

## Example: SMP Parallelization

Franchetti, Voronenko & P, SC 2006

$$\begin{aligned}
 \underbrace{\text{DFT}_{mn}}_{\text{smp}(p,\mu)} &\rightarrow \underbrace{\left( (\text{DFT}_m \otimes I_n) T_n^{mn} (I_m \otimes \text{DFT}_n) L_m^{mn} \right)}_{\text{smp}(p,\mu)} \\
 &\dots \\
 &\rightarrow \underbrace{\left( \text{DFT}_m \otimes I_n \right)}_{\text{smp}(p,\mu)} \underbrace{T_n^{mn}}_{\text{smp}(p,\mu)} \underbrace{\left( I_m \otimes \text{DFT}_n \right)}_{\text{smp}(p,\mu)} \underbrace{L_m^{mn}}_{\text{smp}(p,\mu)} \\
 &\dots \\
 &\rightarrow \underbrace{\left( (L_m^{mp} \otimes I_{n/p\mu}) \otimes I_\mu \right)}_{\left( \bigoplus_{i=0}^{p-1} T_n^{mn,i} \right)} \underbrace{\left( I_p \otimes (\text{DFT}_m \otimes I_{n/p}) \right)}_{\left( I_p \otimes (I_{m/p} \otimes \text{DFT}_n) \right)} \underbrace{\left( (L_p^{mp} \otimes I_{n/p\mu}) \otimes I_\mu \right)}_{\left( I_p \otimes L_{m/p}^{mn/p} \right)} \underbrace{\left( (L_p^{pn} \otimes I_{m/p\mu}) \otimes I_\mu \right)}_{\left( (L_p^{pn} \otimes I_{m/p\mu}) \otimes I_\mu \right)}
 \end{aligned}$$



**load-balanced, no false sharing**

*One rewriting system for every platform paradigm:  
SIMD, distributed memory parallelism, FPGA, ...*

# Same Approach for Different Paradigms

## Threading:

$$\begin{aligned} \frac{\text{DFT}_{mn}}{\text{smp}(p,\mu)} &\rightarrow \frac{\left( (\text{DFT}_m \otimes \text{I}_n) \text{T}_n^{mn} (\text{I}_m \otimes \text{DFT}_n) \text{L}_m^{mn} \right)}{\text{smp}(p,\mu)} \\ &\dots \\ &\rightarrow \frac{\left( \text{DFT}_m \otimes \text{I}_n \right)}{\text{smp}(p,\mu)} \frac{\text{T}_n^{mn}}{\text{smp}(p,\mu)} \frac{\left( \text{I}_m \otimes \text{DFT}_n \right)}{\text{smp}(p,\mu)} \frac{\text{L}_m^{mn}}{\text{smp}(p,\mu)} \\ &\dots \\ &\rightarrow \left( (\text{L}_m^{mp} \otimes \text{I}_{n/p}) \otimes_\mu \text{I}_p \right) \left( \text{I}_p \otimes_\parallel (\text{DFT}_m \otimes \text{I}_{n/p}) \right) \left( (\text{L}_m^{mp} \otimes \text{I}_{n/p}) \otimes_\mu \text{I}_p \right) \\ &\quad \left( \bigoplus_{i=0}^{p-1} \text{T}_n^{mn,i} \right) \left( \text{I}_p \otimes_\parallel (\text{I}_{m/p} \otimes \text{DFT}_n) \right) \left( \text{I}_p \otimes_\parallel \text{L}_{m/p}^{mn/p} \right) \left( (\text{L}_p^m \otimes \text{I}_{m/p}) \otimes_\mu \text{I}_p \right) \end{aligned}$$

## Vectorization:

$$\begin{aligned} \frac{\text{DFT}_{mn}}{\text{vec}(r)} &\rightarrow \frac{\left( (\text{DFT}_m \otimes \text{I}_n) \text{T}_n^{mn} (\text{I}_m \otimes \text{DFT}_n) \text{L}_m^{mn} \right)}{\text{vec}(r)} \\ &\dots \\ &\rightarrow \frac{\left( \text{DFT}_m \otimes \text{I}_n \right)^T}{\text{vec}(r)} \left( \frac{\text{T}_n^{mn}}{\text{vec}(r)} \right)^T \frac{\left( \text{I}_m \otimes \text{DFT}_n \right)}{\text{vec}(r)} \frac{\text{L}_m^{mn}}{\text{vec}(r)} \\ &\dots \\ &\rightarrow \left( \text{I}_{mn/\nu} \otimes \text{L}_\nu^{2\nu} \right) \left( \text{DFT}_m \otimes \text{I}_{n/\nu} \otimes_\parallel \text{I}_\nu \right) \left( \frac{\text{T}_n^{mn}}{\text{vec}(r)} \right)^T \\ &\quad \left( \text{I}_{m/\nu} \otimes (\text{L}_\nu^{2\nu} \otimes \text{I}_\nu) \right) \left( \text{I}_{n/\nu} \otimes (\text{L}_\nu^{2\nu} \otimes \text{I}_\nu) \right) \left( \text{I}_2 \otimes \text{L}_\nu^{2\nu} \right) \left( \text{DFT}_n \otimes \text{I}_\nu \right) \\ &\quad \left( (\text{L}_m^{mn} \otimes \text{I}_2) \otimes \text{I}_\nu \right) \left( \text{I}_{mn/\nu} \otimes \text{L}_\nu^{2\nu} \right) \end{aligned}$$

## GPUs:

$$\begin{aligned} \frac{\left( \text{DFT}_{r,k} \right)}{\text{gpu}(t,c)} &\rightarrow \underbrace{\left( \prod_{i=0}^{k-1} \text{L}_r^{r^k} \left( \text{I}_{r^{k-i-1}} \otimes \text{DFT}_r \right) \left( \text{I}_{r^{k-i-1}} \otimes \text{T}_{r^{k-i-1}}^{r^{k-i}} \right) \text{L}_{r^{k+1}}^{r^k} \right)}_{\text{gpu}(t,c)} \text{R}_r^{r^k} \\ &\dots \\ &\rightarrow \left( \prod_{i=0}^{k-1} \left( \text{L}_r^{r^{n/2}} \otimes \text{I}_2 \right) \left( \text{I}_{r^{n-1}/2} \otimes \times \frac{\left( \text{DFT}_r \otimes \text{I}_2 \right) \text{L}_r^{2r}}{\text{shd}(t,c)} \right) \text{T}_i \right) \\ &\quad \left( \text{L}_r^{r^{n/2}} \otimes \text{I}_2 \right) \left( \text{I}_{r^{n-1}/2} \otimes \times \frac{\text{L}_r^{2r}}{\text{shd}(t,c)} \right) \left( \text{R}_r^{r^{n-1}} \otimes \text{I}_r \right) \end{aligned}$$

## Verilog for FPGAs:

$$\begin{aligned} \frac{\left( \text{DFT}_{r,k} \right)}{\text{stream}(r^*)} &\rightarrow \underbrace{\left[ \prod_{i=0}^{k-1} \text{L}_r^{r^k} \left( \text{I}_{r^{k-i-1}} \otimes \text{DFT}_r \right) \left( \text{I}_{r^{k-i-1}} \otimes \text{T}_{r^{k-i-1}}^{r^{k-i}} \right) \text{L}_{r^{k+1}}^{r^k} \right]}_{\text{stream}(r^*)} \text{R}_r^{r^k} \\ &\dots \\ &\rightarrow \left[ \prod_{i=0}^{k-1} \frac{\text{L}_r^{r^k}}{\text{stream}(r^*)} \left( \text{I}_{r^{k-i-1}} \otimes \text{DFT}_r \right) \left( \frac{\text{L}_r^{r^k}}{\text{stream}(r^*)} \otimes \text{T}_{r^{k-i-1}}^{r^{k-i}} \right) \text{L}_{r^{k+1}}^{r^k} \right] \text{stream}(r^*) \\ &\dots \\ &\rightarrow \left[ \prod_{i=0}^{k-1} \frac{\text{L}_r^{r^k}}{\text{stream}(r^*)} \left( \text{I}_{r^{k-i-1}} \otimes_\delta \left( \text{I}_{r^{k-1}} \otimes \text{DFT}_r \right) \right) \frac{\text{T}_i^r}{\text{stream}(r^*)} \text{R}_r^{r^k} \right] \text{stream}(r^*) \end{aligned}$$

- Rigorous, correct by construction
- Overcomes compiler limitations

## Computer generated Functions for Intel IPP

Intel® Integrated Performance Primitives (Intel® IPP) 6.0

**3984 C functions  
1M lines of code**

Transforms: DFT {fwd+inv}, RDFT {fwd+inv}, DCT2, DCT3, DCT4, DHT, WHT

Sizes: 2–64 (DFT, RDFT, DHT); 2-powers (DCTs, WHT)

Precision: single, double

Data type: scalar, SSE, AVX (DFT, DCT), LRB (DFT)

**Computer generated**

Results: SpiralGen Inc.

## Challenge: General Size Libraries

### So far:

*Code specialized to fixed input size*

```
DFT_384(x, y) {  
    ...  
    for(i = ...) {  
        t[2i] = x[2i] + x[2i+1]  
        t[2i+1] = x[2i] - x[2i+1]  
    }  
    ...  
}
```

- Algorithm fixed
- Nonrecursive code

### Challenge:

*Library for general input size*

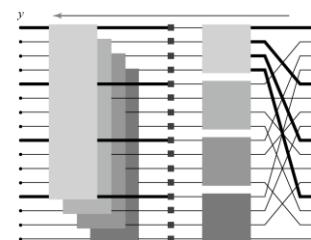
```
DFT(n, x, y) {  
    ...  
    for(i = ...) {  
        DFT_strided(m, x+mi, y+i, 1, k)  
    }  
    ...  
}
```

- Algorithm cannot be fixed
- Recursive code
- Creates many challenges

## Challenge: Recursive Steps Needed

Cooley-Tukey FFT

$$y = (\text{DFT}_k \otimes I_m) T_m^{km} (I_k \otimes \text{DFT}_m) L_k^{km} x$$



Implementation that increases locality (e.g., FFTW 2.x)

```
void DFT(int n, cpx *y, cpx *x) {  
    int k = choose_dft_radix(n);  
  
    for (int i=0; i < k; ++i)  
        DFTrec(m, y + m*i, x + i, k, 1);  
    for (int j=0; j < m; ++j)  
        DFTscaled(k, y + j, t[j], m);  
}
```

## $\Sigma$ -SPL : Basic Idea

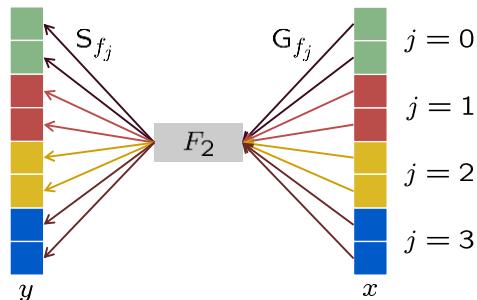
Four additional matrix constructs:  $\Sigma$ ,  $G$ ,  $S$ , Perm

$\Sigma\{\text{sum}\}$	matrix sum (explicit loop)
$G_f\{\text{gather}\}$	load data with index mapping $f$
$S_f\{\text{scatter}\}$	store data with index mapping $f$
$\text{Perm}_f$	permute data with the index mapping $f$

$\Sigma$ -SPL formulas = matrix factorizations

$$\text{Example: } y = (I_4 \otimes F_2)x \rightarrow y = \sum_{j=0}^3 S_{f_j} F_2 G_{f_j} x$$

$$y = \begin{bmatrix} F_2 & & & \\ & F_2 & & \\ & & F_2 & \\ & & & F_2 \end{bmatrix} x$$



## Find Recursion Step Closure

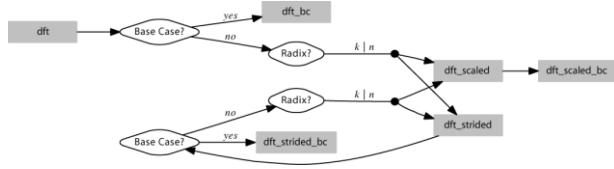
Voronenko, thesis 2008

$$\begin{array}{c}
 \{\text{DFT}_n\} \\
 \downarrow \\
 (\{\text{DFT}_{n/k}\} \otimes I_k) T_k^n (I_{n/k} \otimes \{\text{DFT}_k\}) L_{n/k}^n \\
 \downarrow \\
 \left( \sum_{i=0}^{k-1} S_{h_{i,k}} \{\text{DFT}_{n/k}\} G_{h_{i,k}} \right) \text{diag}(f) \left( \sum_{j=0}^{n/k-1} S_{h_{jk,1}} \{\text{DFT}_k\} G_{h_{jk,1}} \right) \text{perm}(\ell_{n/k}^n) \\
 \downarrow \\
 \sum_{i=0}^{k-1} S_{h_{i,k}} \{\text{DFT}_{n/k}\} \text{diag}(f \circ h_{i,k}) G_{h_{i,k}} \sum_{j=0}^{n/k-1} S_{h_{jk,1}} \{\text{DFT}_k\} G_{h_{j,n/k}} \\
 \downarrow \\
 \sum_{i=0}^{k-1} \left\{ S_{h_{i,k}} \text{DFT}_{n/k} \text{diag}(f \circ h_{i,k}) G_{h_{i,k}} \right\} \sum_{j=0}^{n/k-1} \left\{ S_{h_{jk,1}} \text{DFT}_k G_{h_{j,n/k}} \right\}
 \end{array}$$

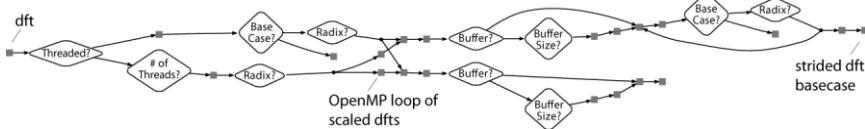
*Repeat until closure*

## Recursion Step Closure: Examples

DFT: scalar code



DFT: full-fledged (vectorized and parallel code)



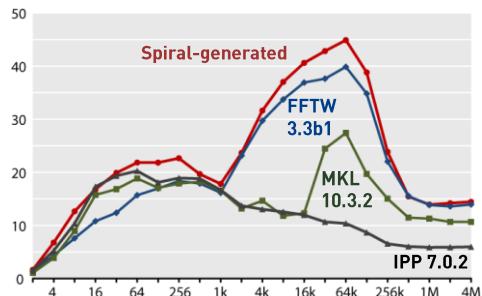
## Generating Dozens of “FFTWs”

$$\begin{aligned}
 \text{DFT}_n &\rightarrow P_{k/2,2m}^T (\text{DFT}_{2m} + (I_{k/2-1} \otimes C_{2m} \text{rDFT}_{2m}(k/k))) (R\text{DFT}_k^T \otimes I_m) \quad k \text{ even}, \\
 \text{RDFT}_n &\rightarrow P_{k/2,2m}^T \left( \begin{array}{c|c} \text{RDFT}_{2m}^T & (\text{DFT}_{2m}^T \otimes I_m) \\ \hline I_{k/2-1} \otimes I_{2m} & (\text{DFT}_{2m}^T \otimes I_m) \end{array} \right) \left( \begin{array}{c|c} \text{RDFT}_k^T & \\ \hline I_{k/2-1} \otimes I_{2m} & \text{DFT}_{2m}^T \otimes I_m \end{array} \right) \quad k \text{ even}, \\
 \text{DHT}_n &\rightarrow (P_{k/2,2m}^T \otimes I_2) \left( \begin{array}{c|c} \text{DHT}_{2m}^T & (\text{DHT}_{2m}^T \otimes I_m) \\ \hline I_{k/2-1} \otimes I_{2m} & (\text{DHT}_{2m}^T \otimes I_m) \end{array} \right) \left( \begin{array}{c|c} \text{DHT}_k^T & \\ \hline I_{k/2-1} \otimes I_{2m} & \text{DHT}_{2m}^T \otimes I_m \end{array} \right) \quad k \text{ even}, \\
 \text{IDFT}_n(a) &\rightarrow I_m^T \left( I_k \otimes \left( \begin{array}{c|c} \text{IDFT}_{2m}(k+1/k) & (\text{IDFT}_{2m}^T(a)) \otimes I_m \\ \hline I_{k/2-1} \otimes I_{2m} & (\text{IDFT}_{2m}^T(a)) \otimes I_m \end{array} \right) \right) (R\text{DFT}_k^T \otimes I_m), \\
 \text{rDFT}_n &\rightarrow (Q_{k/2,2m}^T \otimes I_2) (I_k \otimes (\text{rDFT}_{2m}(k+1/k))) (R\text{DFT}_k^T \otimes I_m), \quad k \text{ even}, \\
 \text{RDFT-3} &\rightarrow (Q_{k/2,2m}^T \otimes I_2) (\text{DFT}_{2m}^T \otimes I_2 \otimes R\text{DFT-3}_2^T) B_n(I_{k/2}^T \otimes I_2) (I_m \otimes R\text{DFT}_k^T) Q_{m/2,k}, \\
 \text{DCT-2} &\rightarrow P_{k/2,2m}^T (\text{DCT}_{2m}^T \otimes I_2)^T \oplus (I_{k/2-1} \otimes N_{2m} \text{RDFT-3}_2^T) B_n(I_{k/2}^T \otimes I_2) (I_m \otimes R\text{DFT}_k^T) Q_{m/2,k}, \\
 \text{DCT-3} &\rightarrow \text{DCT-2}^T, \\
 \text{DCT-4} &\rightarrow Q_{k/2,2m}^T (I_{k/2} \otimes N_{2m} \text{RDFT-3}_2^T) B_n(I_{k/2}^T \otimes I_2) (I_m \otimes R\text{DFT}_k^T) Q_{m/2,k}, \\
 \text{DFT}_n &\rightarrow (\text{DFT}_1 \otimes I_m) I_m^T (I_k \otimes \text{DFT}_m) I_m^T, \quad n = km, \\
 \text{IDFT}_n &\rightarrow P_n(\text{DFT}_1^T \otimes \text{DFT}_m^T) I_m^T, \quad n = km, \quad \text{gcd}(k,m) = 1, \\
 \text{DFT}_n &\cdot P_n^T (I_1 \otimes \text{DFT}_p) (I_{2m} \otimes I_p) \text{DFT}_p^T, \quad p \text{ prime}, \\
 \text{DCT-3}_n &\rightarrow (I_{k-1} \otimes I_m) I_m^T (\text{DCT-3}_n \otimes I_k) (I_k \otimes \text{DCT-3}_n^T) (I_k \otimes \text{DCT-3}_n^T), \\
 &\quad (F_2 \otimes I_m) \left[ \begin{array}{c|c} 0 & -J_{k-1} \\ \hline 1 & 0 \otimes I_{k-1} \end{array} \right], \quad n = 2m, \\
 \text{DCT-4}_n &\rightarrow S_n \text{DCT-2}_n \otimes \text{diag}_{k=1}^{k=n} ((1/(2\cos((2k+1)\pi/4n)))) \\
 \text{IMDCT}_{2m} &\rightarrow (J_m + I_m \cdots I_m + J_m) \left( \begin{array}{c|c} 0 & 1 \\ \hline 1 & 0 \otimes I_m \end{array} \right) \left( \begin{array}{c|c} -1 & 0 \\ \hline 0 & 1 \otimes I_m \end{array} \right) J_{2m} \text{DCT-4}_{2m}, \\
 \text{WHT}_n &\rightarrow \prod_{k=1}^n (Q_{k-1} \cdots I_{k-1} \otimes \text{WHT}_2^T \otimes I_{2(k+1)} \cdots I_m), \quad k = k_1 + \cdots + k_j, \\
 \text{DFT}_2 &\rightarrow \frac{I_2}{\sqrt{2}}, \\
 \text{DCT-2}_2 &\rightarrow \text{diag}(1/\sqrt{2}) I_2, \\
 \text{DCT-4}_2 &\rightarrow \frac{I_2}{\sqrt{2}} I_{13/8}.
 \end{aligned}$$

Transform	Code size	
	non-parallelized	parallelized
no vectorization		
DFT	13.1 KLOC / 0.59 MB	10.3 KLOC / 0.45 MB
RDFT	8.5 KLOC / 0.36 MB	8.8 KLOC / 0.39 MB
DHT	9.1 KLOC / 0.40 MB	9.4 KLOC / 0.39 MB
DCT-2	12.0 KLOC / 0.55 MB	12.4 KLOC / 0.57 MB
DCT-3	12.0 KLOC / 0.56 MB	12.3 KLOC / 0.59 MB
DCT-4	6.8 KLOC / 0.33 MB	7.1 KLOC / 0.35 MB
WHT	5.6 KLOC / 0.21 MB	—
2-seq vectorization		
DFT	14.8 KLOC / 0.73 MB	15.0 KLOC / 0.74 MB
RDFT	15.6 KLOC / 0.76 MB	16.0 KLOC / 0.81 MB
scaled RDFT	16.0 KLOC / 0.78 MB	
DHT	16.0 KLOC / 0.83 MB	17.2 KLOC / 0.87 MB
DCT-2	20.7 KLOC / 1.10 MB	21.0 KLOC / 1.00 MB
DCT-3	20.7 KLOC / 1.10 MB	20.9 KLOC / 1.00 MB
DCT-4	7.8 KLOC / 0.47 MB	8.1 KLOC / 0.50 MB
WHT	6.9 KLOC / 0.32 MB	5.8 KLOC / 0.26 MB
FIR Filter	167 KLOC / 7.75 MB	120 KLOC / 5.12 MB
Downsampled FIR Filter	100 KLOC / 4.2 MB	68 KLOC / 2.76 MB
4-seq vectorization		
DFT	17.9 KLOC / 1.09 MB	18.2 KLOC / 1.11 MB
RDFT	16.2 KLOC / 0.86 MB	16.5 KLOC / 0.91 MB
scaled RDFT	16.5 KLOC / 0.88 MB	
DHT	17.9 KLOC / 1.08 MB	18.3 KLOC / 1.04 MB
DCT-2	22.3 KLOC / 1.57 MB	23.6 KLOC / 1.58 MB
DCT-3	32.0 KLOC / 2.17 MB	32.3 KLOC / 2.29 MB
DCT-4	8.3 KLOC / 0.63 MB	8.5 KLOC / 0.64 MB
WHT	8.5 KLOC / 0.34 MB	6.0 KLOC / 0.14 MB
2D DFT	20.6 KLOC / 1.92 MB	20.8 KLOC / 1.93 MB
3D DFT-2	27.0 KLOC / 2.1 MB	27.2 KLOC / 2.11 MB
FIR Filter	109 KLOC / 5.69 MB	74 KLOC / 3.44 MB
Downsampled FIR Filter	151 KLOC / 7.7 MB	92 KLOC / 4.61 MB

# It Really Works

DFT on Sandybridge (3.3 GHz, 4 Cores, AVX)  
Performance [Gflop/s]

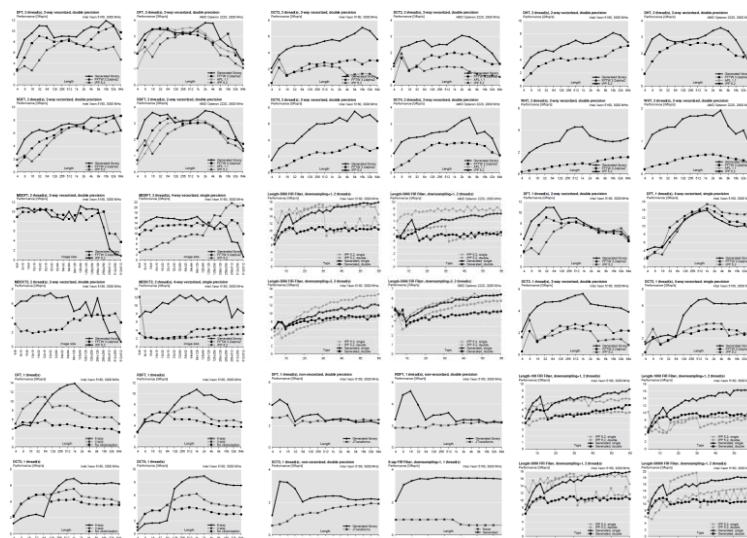


$\text{DFT}_n \rightarrow (\text{DFT}_k \otimes I_m) T_m^0 (I_k \otimes \text{DFT}_m) L_k^n$   
 $\text{DFT}_n \rightarrow P_{k/2,2m}^1 (\text{DFT}_{2m} \oplus (I_{k/2-1} \otimes_i C_{2m} r\text{DFT}_{2m}(i/k))) (\text{RDFT}_k \otimes I_m)$   
 $\text{RDFT}_n \rightarrow (P_{k/2,2m} \otimes I_2) (\text{RDFT}_{2m} \oplus (I_{k/2-1} \otimes_i D_{2m} r\text{DFT}_{2m}(i/k))) (\text{RDFT}_k \otimes I_m)$   
 $r\text{DFT}_{2n}(u) \rightarrow L_m^{2n} (I_k \otimes r\text{DFT}_{2m}((1+u)/k)) (r\text{DFT}_{2k}(u) \otimes I_m)$

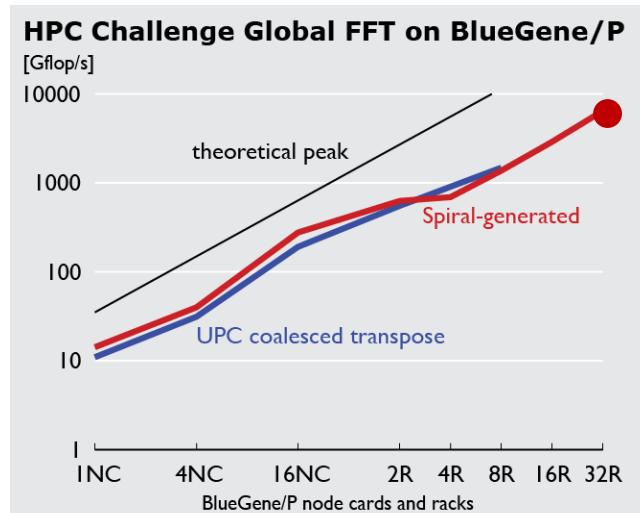


vectorized, threaded,  
platform-tuned, adaptive library  
(5 MB source code)

## Generating Dozens of “FFTWs”



## Very Large Scale: BG/P



6.4 Tflop/s

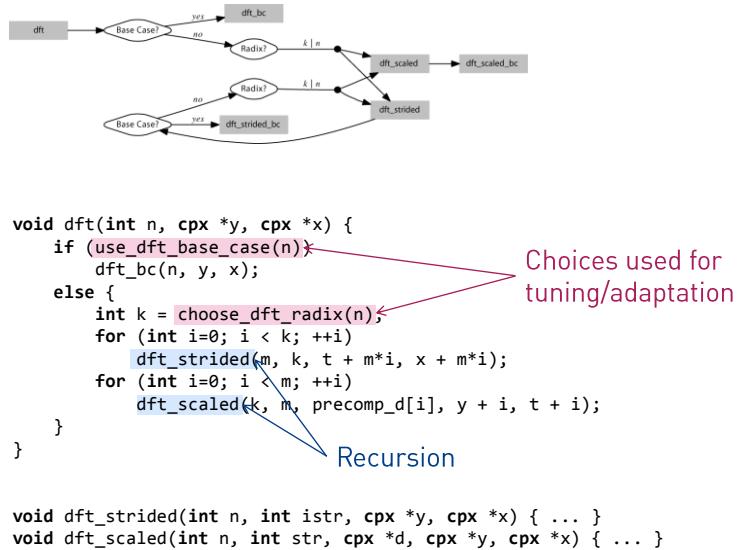
32 racks  
= 32K node cards  
= 128K cores

Is everything automated?

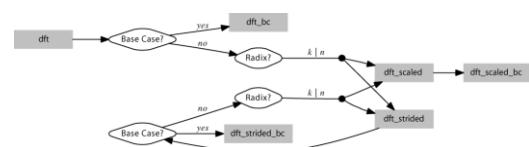
Yes, except efficient tuning

32

## Simple Generated Library (~FFTW 2.x)



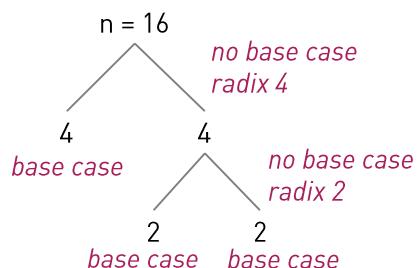
## FFT Search Space (Simple Library)



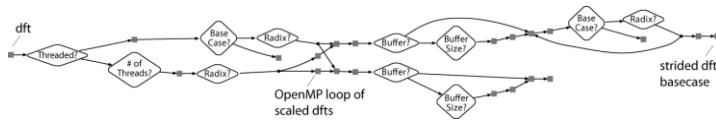
Recursive choice:

$$n = 2^k \quad \begin{matrix} \text{base case?} \\ \text{radix?} \end{matrix}$$

Example selections for  $n = 16$ :



## FFT Search Space (The Real Thing)

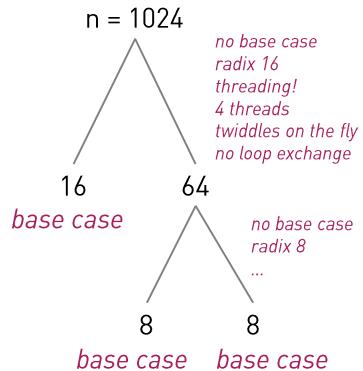


Recursive choice:

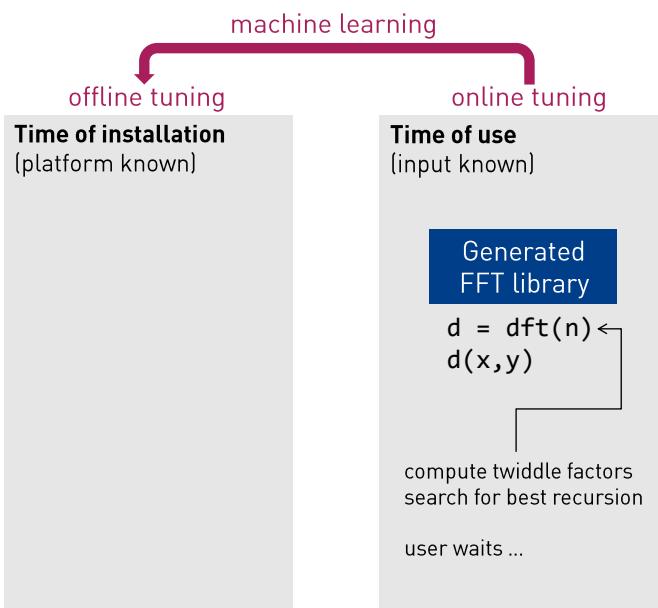
$n = 2^k$

- base case?
- radix?
- threading?
- #threads?
- twiddles?
- loop exchange?

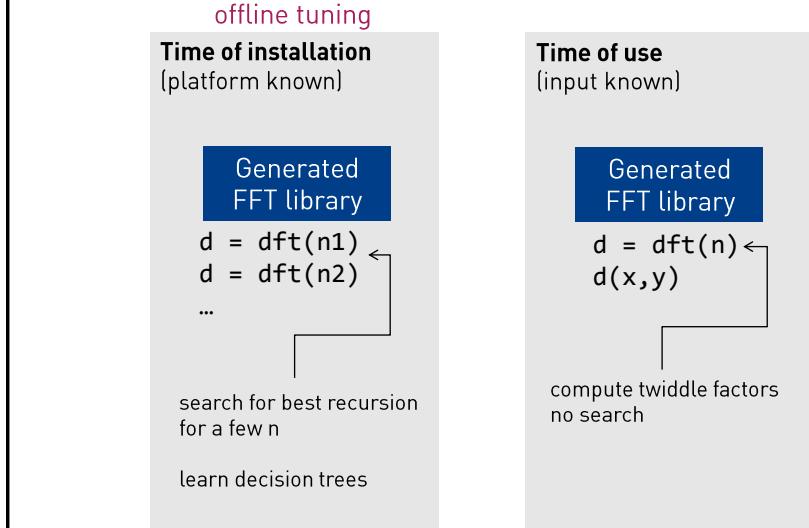
Example selections for  $n = 1024$ :



## When to Tune?



## When to Tune?



## Online Tuning → Offline Tuning

At installation time, run search for a few  $n$

Learn decision trees

Insert into library

```
void dft(int n, cpx *y, cpx *x) {
    if (use_dft_base_case(n))
        dft_bc(n, y, x);
    else {
        int k = choose_dft_radix(n);
        for (int i=0; i < k; ++i)
            dft_strided(m, k, t + m*i, x + m*i);
        for (int i=0; i < m; ++i)
            dft_scaled(k, m, precomp_d[i], y + i, t + i);
    }
    void dft_strided(int n, int istr, cpx *y, cpx *x) { ... }
    void dft_scaled(int n, int str, cpx *d, cpx *y, cpx *x) { ... }
}
```

Choices used for tuning/adaptation

## Online Tuning → Offline Tuning

At installation time, run search for a few n

Learn decision trees

Insert into library

```
void dft(int n, cpx *y, cpx *x) {
    if (use_dft_base_case(n))
        dft_bc(n, y, x);
    else {
        int k = choose_dft_radix(n);
        for (int i=0; i < k; ++i)
            dft_strided(m, k, t + m*i, x + m*i);
        for (int i=0; i < m; ++i)
            dft_scaled(k, m, precomp_d[i], y + i, t + i);
    }
}
void dft_strided(int n, int istr, cpx *y, cpx *x) { ... }
void dft_scaled(int n, int str, cpx *d, cpx *y, cpx *x) { ... }
```

Example decision tree

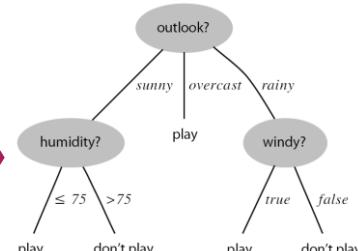
```
if ( n <= 65536 ) {
    if ( n <= 32 ) {
        if ( n <= 4 ) {return 2;}
        else {return 4;}
    }
    else {
        if ( n <= 1024 ) {
            if ( n <= 256 ) {return 8;}
            else {return 32;}
        }
        else {
            .....
        }
    }
}
```

## Decision Tree Generation: C4.5

*Features (events)*

Outlook	Temperature	Humidity	Windy	Decision
sunny	85	85	false	don't play
sunny	80	90	true	don't play
overcast	83	78	false	play
rain	70	96	false	play
rain	68	80	false	play
rain	65	70	true	don't play
overcast	64	65	true	play
sunny	72	95	false	don't play
sunny	69	70	false	play
rain	75	80	false	play
sunny	75	70	true	play
overcast	72	90	true	play
overcast	81	75	false	play
rain	71	80	true	don't play

C4.5



$P[\text{play}|\text{windy}=\text{false}] = 6/8$   
 $P[\text{don't play}|\text{windy}=\text{false}] = 2/8$   
 $P[\text{play}|\text{windy}=\text{true}] = 1/2$   
 $P[\text{don't play}|\text{windy}=\text{false}] = 1/2$

*Entropy of Features*  
 $H[\text{windy}] = 0.89$   
 $H[\text{outlook}] = 0.69$   
 $H[\text{humidity}] = \dots$

## Application to Libraries

Features = arguments of functions (except variable pointers)

```
dft(int n, cpx *y, cpx *x)  
dft_strided(int n, int istr, cpx *y, cpx *x)  
dft_scaled(int n, int str, cpx *d, cpx *y, cpx *x)  
etc.
```

## Experimental Setup

3GHz Intel Xeon 5160 (2 Core 2 Duos = 4 cores)

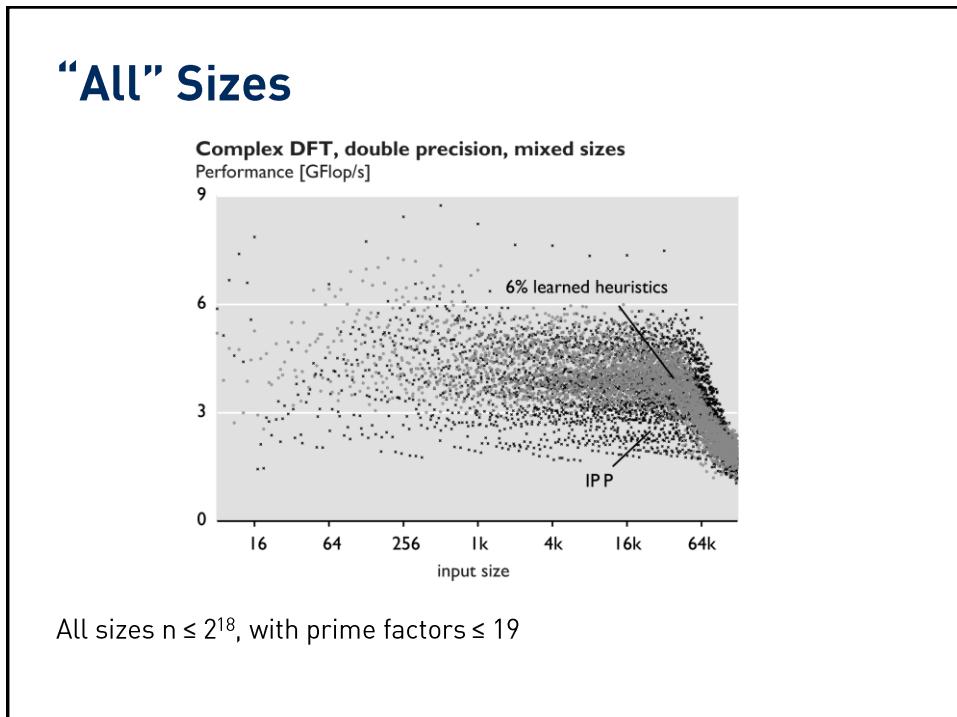
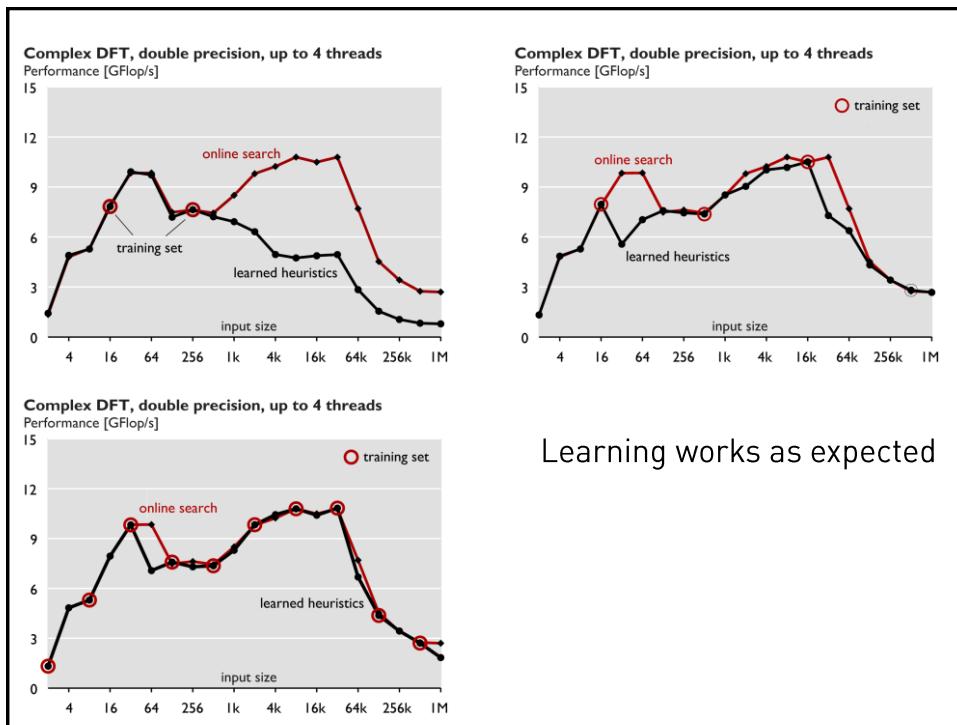
icc 10.1

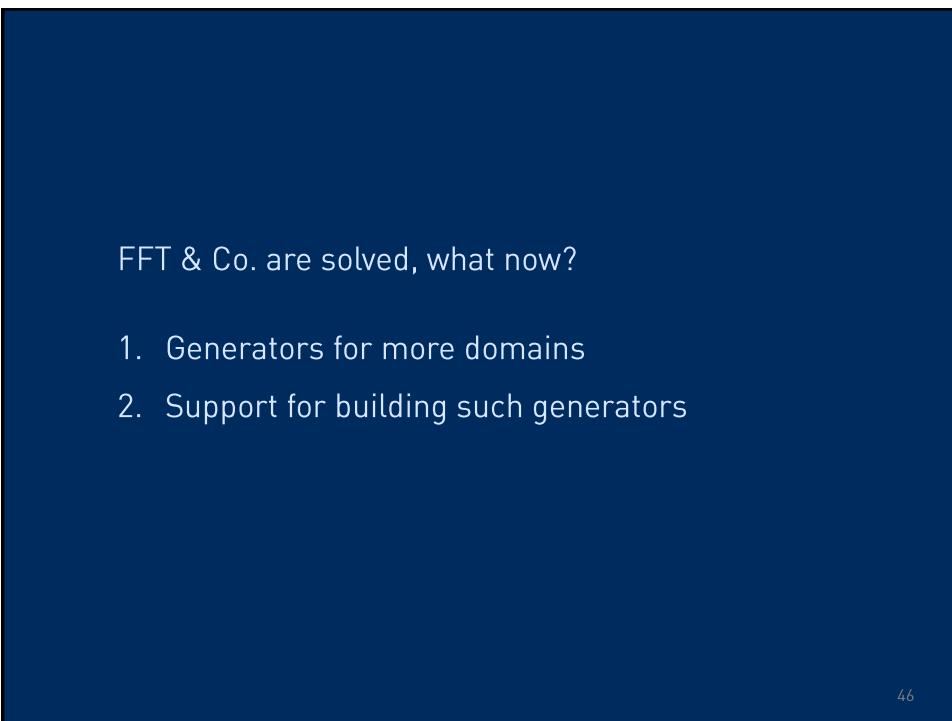
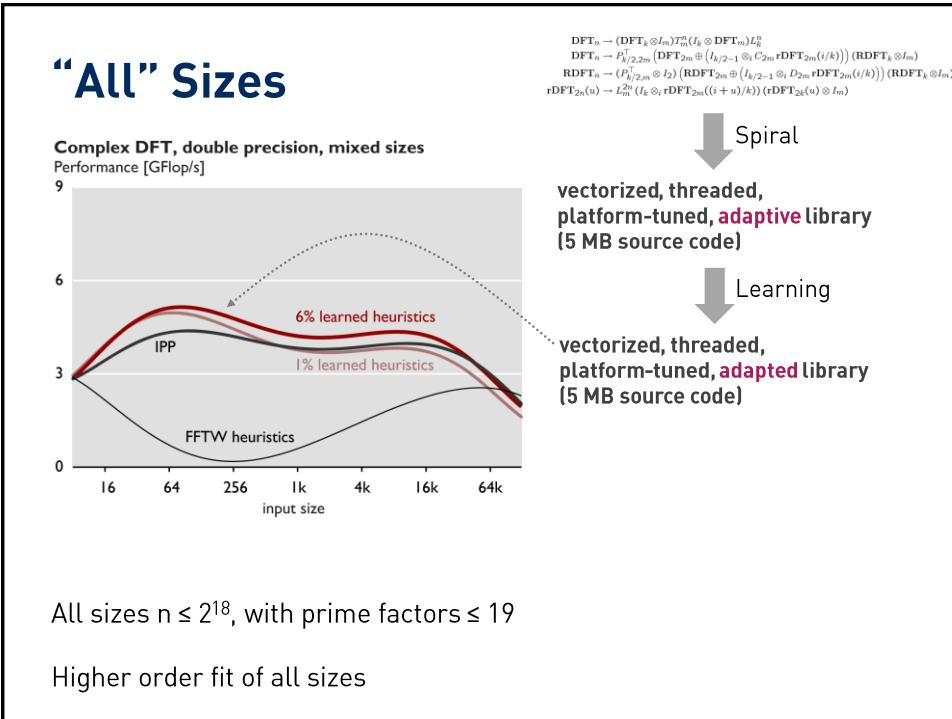
Spiral-generated “FFTW” [Voronenko et al., CGO, 2009]:

*Recursive choice:*

$n = 2^k$

- base case?*
- radix?*
- threading?*
- #threads?*
- twiddles?*
- loop exchange?*







## LGen: Generator for Basic Linear Algebra

Spampinato & P, CGO 2014

$$\text{BLAC} \quad y = x^T(A + B)y + \delta$$

**Algorithm: Tiling decision and propagation (LL)**

$$[y = x^T(A + B)y + \delta]_{2,3}$$

**Algorithm (-LL)**

$$\sum_{i,j,i',j'} S_i S_{i'} (G_{i'} G_i A G_j G_{j'}) (G_{j'} G_j x) \dots$$

**C Program**

```
void kernel(float *x, float *A, float *B, ...) {
    float t0_64_0, t0_64_1, t0_64_2, t0_64_3 ...
    t0_57_0 = A[0];
    t0_56_0 = A[1];
    ...
    t0_59_0 = t0_57_0 + t0_33_0;
    t0_63_0 = t0_59_0 * t0_9_0;
    t0_59_1 = t0_56_0 + t0_32_0;
    t0_60_0 = t0_59_1 * t0_8_0;
    < many more lines>
```

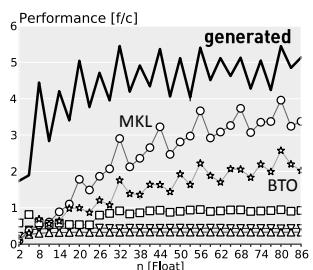
vectorization

locality optimization

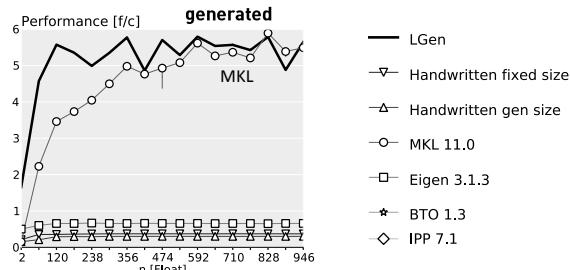
code style  
code level optimization

## LGen: Sample Results

$$C = \alpha AB + \beta C$$



$$C = \alpha(A_0 + A_1)^T B + \beta C$$



$$A \in \mathbb{R}^{n \times 4}$$

$$B \in \mathbb{R}^{4 \times n}$$

$$A_0 \in \mathbb{R}^{4 \times 4}$$

$$B \in \mathbb{R}^{4 \times n}$$

# PL Support: Example Code Style

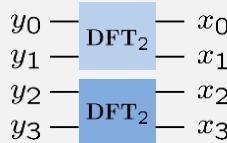
Openbeck, Rompf, Stojanov, Odersky & P, GPCE 2012



**SPL**

$$y = (\mathbf{I}_2 \otimes \text{DFT}_2)x$$

**Data flow graph**



**Scala function**

```
def f(x: Array[Double], y: Array[Double]) = {
  for (i <- 0 until 2) {
    y(2*i) = x(i*2) + x(i*2+1)
    y(2*i+1) = x(i*2) - x(i*2+1)
  }
}
```

```
def f(x: Array[Rep[Double]], y: Array[Rep[Double]]) = {
  for (i <- 0 until 2) {
    y(2*i) = x(i*2) + x(i*2+1)
    y(2*i+1) = x(i*2) - x(i*2+1)
  }
}
```

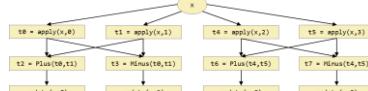


**scalarized**

```
t0 = s0 + s1;
t1 = s0 - s1;
t2 = s2 + s3;
t3 = s2 - s3;
```

*unrolled, scalar repl.*

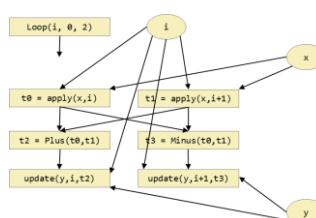
```
def f(x: Rep[Array[Double]], y: Rep[Array[Double]]) = {
  for (i <- 0 until 2) {
    y(2*i) = x(i*2) + x(i*2+1)
    y(2*i+1) = x(i*2) - x(i*2+1)
  }
}
```



```
t0 = x[0];
t1 = x[1];
t2 = t0 + t1;
y[0] = t2;
t3 = t0 - t1;
y[1] = t3;
t4 = x[0];
t5 = x[1];
t6 = t4 + x5;
y[0] = t6;
t7 = t4 - x5;
y[3] = t7;
```

*looped, scalar repl.*

```
def f(x: Rep[Array[Double]], y: Rep[Array[Double]]) = {
  for (i <- 0 until 2: Rep[Range]) {
    y(2*i) = x(i*2) + x(i*2+1)
    y(2*i+1) = x(i*2) - x(i*2+1)
  }
}
```



```
for (int i=0; i < 2; i++)
{
  t0 = x[i];
  t1 = x[i+1];
  t2 = t0 + t1;
  y[i] = t2;
  t3 = t0 - t1;
  y[i+1] = t3;
}
```

```

def f(x: Array[Rep[Double]],
      y: Array[Rep[Double]]) = {
  for (i <- 0 until 2) {
    y(2*i) = x(i*2) + x(i*2+1)
    y(2*i+1) = x(i*2) - x(i*2+1)
  }
}

```



*scalarized*

```

t0 = s0 + s1;
t1 = s0 - s1;
t2 = s2 + s3;
t2 = s2 - s3;

```

## *Staging enables program generation*

*Abstracting over code style =  
abstracting over staging decisions*

```

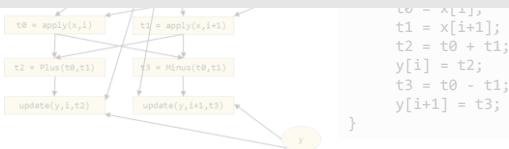
def f[L[_],A[_],T](looptype: L, x: A[Array[T]], y: A[Array[T]]) = {
  for (i <- 0 until 2: L[Range]) {
    y(2*i) = x(i*2) + x(i*2+1)
    y(2*i+1) = x(i*2) - x(i*2+1)
  }
}

```

```

y: Rep[Array[Double]] = 
for (i <- 0 until 2: Rep[Range]) {
  y(2*i) = x(i*2) + x(i*2+1)
  y(2*i+1) = x(i*2) - x(i*2+1)
}

```



```

t0 = x[i];
t1 = x[i+1];
t2 = t0 + t1;
y[i] = t2;
t3 = t0 - t1;
y[i+1] = t3;
}

```

## Related Work

Program generators for performance

[FFTW codelet generator](#) (Frigo)

[Flame](#) (van de Geijn Quinta, na-Orti, Bientinesi, ...)

[cvxgen](#) (Mattingley, Boyd)

PetaBricks (Ansel, Amarasinghe, ...)

Spiral

Autotuning

ATLAS/PhiPAC (Whaley, Bilmes, Demmel, Dongarra, ...)

FFTW adaptive library (Frigo, Johnson)

OSKI (Vuduc et al.)

Adaptive sorting (Li et al.)

Environments for DSLs and program generation

[Scala](#) and [lightweight](#) modular [staging](#) ([LMS](#))

[More examples](#)

# Automatically from Math to Fast Code

## Principles

Generate Code

Capturing algorithm knowledge:  
*Mathematical DSLs*



Structural optimization:  
*Rewriting*

$$\begin{aligned} \text{DFT}_n &\rightarrow (\text{DFT}_k \otimes \text{I}_m) \text{T}_m^n (\text{I}_k \otimes \text{DFT}_m) \text{U}_k^n, \quad n = km \\ \text{DFT}_n &\rightarrow P_n(\text{DFT}_k \otimes \text{DFT}_m) Q_n, \quad n = km, \quad \gcd(k, m) = 1 \\ \text{DCT-4}_n &\rightarrow S_n \text{DCT-2}_n \text{diag}_{0 \leq k < n} (1/(2 \cos((2k+1)\pi/4n))) \\ \text{IMDCT}_{2m} &\rightarrow (\text{J}_m \oplus \text{I}_m \oplus \text{L}_m \oplus \text{J}_m) \left( \begin{pmatrix} 1 \\ -1 \end{pmatrix} \otimes \text{I}_m \right) \oplus \left( \begin{pmatrix} 1 \\ -1 \end{pmatrix} \otimes \text{I}_m \right) \text{J}_{2m} \text{DCT-4}_{2m} \end{aligned}$$

Decision making:  
*Search and learning*

$$\underbrace{\text{A}_m \otimes \text{I}_n}_{\text{smp}(p,\mu)} \rightarrow \underbrace{\text{L}_m^{mn}}_{\text{smp}(p,\mu)} (\text{I}_p \otimes \|(\text{I}_{n/p} \otimes \text{A}_m)) \underbrace{\text{L}_n^{mn}}_{\text{smp}(p,\mu)}$$

## Key Challenges

New domains (linear algebra, filters, ...)

Programming language support (DSLs, staging)

More information: [www.spiral.net](http://www.spiral.net)

## Further Reading

### Spiral ([www.spiral.net](http://www.spiral.net))

Markus Püschel, Franz Franchetti and Yevgen Voronenko

**Spiral**

in Encyclopedia of Parallel Computing, Eds. David Padua, Springer 2011

Georg Ofenbeck, Tiark Rompf, Alen Stojanov, Martin Odersky and Markus Püschel

**Spiral in Scala: Towards the Systematic Construction of Generators for Performance Libraries**

Proc. International Conference on Generative Programming: Concepts & Experiences [GPCE], pp. 125-134, 2013

Markus Püschel, José M. F. Moura, Jeremy Johnson, David Padua, Manuela Veloso, Bryan Singer, Jianxin Xiong, Franz Franchetti, Aca

Gacic, Yevgen Voronenko, Kang Chen, Robert W. Johnson, and Nick Rizzolo

**SPiRAL: Code Generation for DSP Transforms**

Proceedings of the IEEE special issue on "Program Generation, Optimization, and Adaptation," Vol. 93, No. 2, 2005, pp. 232-275

### LGen

Danièle G. Spampinato and Markus Püschel

**A Basic Linear Algebra Compiler**

Proc. International Symposium on Code Generation and Optimization [CGO], pp. 23-32, 2014

Danièle G. Spampinato and Markus Püschel

**A basic linear algebra compiler for structured matrices**

Proc. International Symposium on Code Generation and Optimization [CGO], pp. 117-127, 2016

### Tuning through machine learning

Frédéric de Mesmay, Yevgen Voronenko and Markus Püschel

**Offline Library Adaptation Using Automatically Generated Heuristics**

Proc. International Parallel and Distributed Processing Symposium [IPDPS], pp. 1-10, 2010

Frédéric de Mesmay, Arpad Rimmel, Yevgen Voronenko and Markus Püschel

**Bandit-Based Optimization on Graphs with Application to Library Performance Tuning**

Proc. International Conference on Machine Learning [ICML], pp. 729-736, 2009

Bryan Singer and Manuela Veloso

**Learning to Generate Fast Signal Processing Implementations**

Proc. International Conference on Machine Learning [ICML], pp. 529-536, 2001